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# ABSTRACT

This application report describes how C and assembler code can be used together in an application that uses an MSP430<sup>™</sup> microcontroller (MCU). The combination of C and assembler benefits the designer, because it can provide the power of a high-level language and the speed, efficiency, and low-level control of assembler.

Source code for the examples that are described in this application report can be downloaded from www.ti.com/lit/zip/slaa140.

Contents

# Mixing C and Assembler With MSP430<sup>™</sup> MCUs

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TEXAS INSTRUMENTS



MSP430

Application Report

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### 1 Definition of the C-Compiler for Passing Variables Between Functions

#### 1.1 Stack Frames and Parameter Passing

Each function call creates a stack frame (see Figure 1).

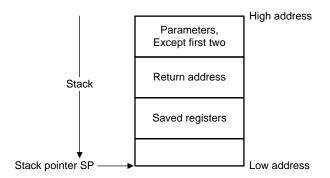


Figure 1. Parameter Passing From C

The parameters of a called function are passed to an assembler routine in a right-to-left order. The two leftmost parameters are passed in registers unless they are defined as a struct or union type, in which case they are also passed on the stack. The remaining parameters are always passed on the stack. See the following example of a call:

f(w,x,y,z)

### 1.2 Calling Convention – Register Use With the IAR C-Compiler

The compiler uses two groups of processor registers.

- The scratch registers R12 to R15 are used for parameter passing and are not normally preserved across the call. If R8 to R11 are used to hold a 64-bit parameter, these registers are also not preserved.
- The other general-purpose registers, R4 to R11, are mainly used for register variables and temporary results and must be preserved across a call. Within C this is handled automatically.

**NOTE:** The *-ur45* or *--lock\_r4* and *--lock\_r5* option prevents the compiler from using registers R4 and R5.

| Argument | 8-Bit or 16-Bit Type | 32-Bit Type  | 64-Bit Type     | Struct or Union |
|----------|----------------------|--------------|-----------------|-----------------|
| 4th (z)  | R15                  | On the stack | On the stack    | On the stack    |
| 3th (y)  | R14                  | On the stack | On the stack    | On the stack    |
| 2nd (x)  | R13                  | R15:R14      | R11:R10:R8:R8   | On the stack    |
| 1st (w)  | R12                  | R12:R13      | R15:R14:R13:R12 | On the stack    |
| Result   | R12                  | R12:R13      | R15:R14:R13:R12 | On the stack    |

| Table 1  | Location | of Decod  | Parameters |
|----------|----------|-----------|------------|
| Table 1. | Location | of Passed | Parameters |

**NOTE:** IAR also support an older calling convention (version 1). For details, refer to the IAR C Compiler documentation

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Definition of the C-Compiler for Passing Variables Between Functions

# 1.3 Calling Convention – Register Use With the CCS C-Compiler

The compiler uses two groups of processor registers.

- The scratch registers R11 to R15 are used for parameter passing and are not normally preserved across the call.
- The other general-purpose registers, R4 to R10, are mainly used for register variables and temporary results and must be preserved across a call. Within C, this is handled automatically.
  - **NOTE:** The *--global\_register=r4* and *--global\_register=r5* options prevent the compiler from using registers R4 and R5, respectively.

| Argument | 8-Bit or 16-Bit Type | 32-Bit Type  | 64-Bit Type     | Struct or Union |
|----------|----------------------|--------------|-----------------|-----------------|
| 4th (z)  | R15                  | On the stack | On the stack    | Depends on size |
| 3th (y)  | R14                  | On the stack | On the stack    | Depends on size |
| 2nd (x)  | R13                  | R15:R14      | On the stack    | Depends on size |
| 1st (w)  | R12                  | R12:R13      | R15:R14:R13:R12 | Depends on size |
| Result   | R12                  | R12:R13      | R15:R14:R13:R12 | Depends on size |

Table 2. Location of Passed Parameters

Also see the Function Structure and Calling Conventions section of MSP430 Optimizing C/C++ Compiler.

# 1.4 Interrupt Functions

Interrupt functions written in C automatically preserve the scratch registers, SR (status register), and the following registers:

IAR: R4 to R11 CCS: R4 to R10

The status register is saved as part of the interrupt calling process. Any registers used by the routine are then saved using push Rxx instructions. On exit, these registers are recovered using pop Rxx instructions, and the RETI instruction is used to reload the status register and return from the interrupt.

Functions written in assembler must explicitly manage these saves and restores.

### 2 Requirements of Assembler Routines to Support Calls From C

An assembler routine that is to be called from C must:

- Conform to the calling convention described above.
- Have a PUBLIC entry-point label.
- Be declared as external before any call, to allow type checking and optional promotion of parameters, as in extern int foo() or extern int foo(int i, int j).

# 2.1 Local Storage Allocation

If the routine needs local storage, the routine allocates the storage in the following ways:

- On the hardware stack
- In static workspace (if the routine is not required to be simultaneously reusable (re-entrant))

IAR: Functions can always use R12 to R15 without saving them and R6 to R11 if they are pushed before use. R4 and R5 must not be used for ROM monitor compatible code. If the C code is compiled with the *-ur45* option, but the application is not to run in the ROM monitor, then it is possible to use R4 and R5 in the assembler routine without saving them, because the C code never uses them.

CCS: Functions can always use R12 to R15 without saving them and R6 to R11 if they are pushed before use. R4 and R5 must not be used for ROM monitor compatible code.



#### 2.2 Interrupt Functions

The calling convention cannot be used for interrupt functions, because the interrupt may occur during the calling of a foreground function. The requirements for an interrupt function routine are different from those of a normal function routine as follows:

- The routine must preserve all used registers, including scratch registers R12 to R15.
- The routine must exit using RETI.
- The routine must treat all flags (Carry, Negative, Zero, and Overflow) of the Status register as undefined.

#### 2.3 Define Interrupt Vectors

As an alternative to defining a C interrupt function in assembly language as described above, the user can assemble an interrupt routine and install it directly in the interrupt vector.

The interrupt vectors are located in the INTVEC segment.

#### 3 Combining C and Assembler Functions

#### 3.1 General Basics

The mechanics to combine C and assembler functions are fairly straightforward. Basically C code that is in .c files imports labels exported by the assembler files using the extern keyword. Assembler codes within .s43 or .asm files export labels to the C code using the PUBLIC keyword. Assembler code import labels exported by C code using the EXTERN keyword. No keyword is required to export C labels to assembler code.

When the .c and .s43 or .asm files are written, they must be added to the project before the project is built. See the .c, .s43, .asm, and project (.ewp or .project) example files included with this application report. See the CCS and IAR documentation for a more complete description of this process.

#### 3.2 Call Assembler Functions Without Parameters to Pass

If no parameters are passed between the C code and the assembler function, a simple call instruction can be used. See the Example 1 code.

#### 3.3 Call Assembler Functions With Parameters to Pass

To pass parameters from C to the assembler function, the parameters must be located as described in the Stack Frames and Parameter Passing section.

The Example 2 code shows how parameters are passed between the C main program and an assembler function.

#### 3.4 Define an Interrupt Service Routine in Assembler

To optimize the interrupt service routine for speed, use assembler. See the Interrupt Functions section for the requirements of an assembler interrupt service routine.

The Example 4 code shows a watchdog interrupt service routine written in assembler that is used from a C program.

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# 3.5 Define an Interrupt Service Routine for Special Interrupts

Some modules (for example, Timer\_A, Timer\_B, and ADC12) use a special combination of hardware and software to detect the source of an individual interrupt. For additional information, see the family user's guide:

- MSP430x1xx Family User's Guide
- MSP430x4xx Family User's Guide
- MSP430F5xx and MSP430F6xx Family User's Guide
- MSP430FR4xx and MSP430FR2xx Family User's Guide
- MSP430FR58xx, MSP430FR59xx, and MSP430FR6xx Family User's Guide

The interrupt service routine for these modules sometimes needs to be written in assembler. The Example 5 code shows how this can be done.

### 3.6 Call C Functions from Assembler

An application can also call a C function from an assembler routine. The same restrictions described in Section 1 apply.

In the Example 3 code, the assembler program calls the C function rand().

# 3.7 Exit Low-Power Mode While in the Interrupt Service Routine

During an interrupt service routine, the status register and the return address are stored on the stack (see the family user's guide for more detailed information). To set the CPU to active mode after returning from the interrupt service routine, modify the value of the status register on the stack (specifically, clear the bits that specify the low-power mode). From C, it is not possible to directly access the stack pointer, but the intrinsic function \_\_bic\_SR\_register\_on\_exit(bits) can modify the status register that is saved on the stack.



**Revision History** 

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Page

# **Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

| Changes | f    | Echruczy | ົ່ວວ | 2002 10 | A   | ו••• 7 | 2010   |
|---------|------|----------|------|---------|-----|--------|--------|
| Changes | TOIL | repruary | 20.  |         | AUG | JUST / | . 2010 |
|         |      |          |      |         |     |        |        |

| • | Editorial and formatting updates throughout document; clarified features that apply to CCS or IAR                 | 1 |
|---|---|---|
|   | Removed former Section 4 Building Libraries, Section 5 Using Watch Windows With Assembler Variables, and Appendix |   |
|   | of code listings  | 5 |

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